

Undulated silicene and germanene freestanding layers: why not?

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Abstract

Silicene and germanene freestanding layers are usually described as a honeycomb lattice formed by two hexagonal sub-lattices presenting a height difference, namely the layer buckling. In this work, first-principles calculations show that silicene and germanene can be rippled at 0 K with various wavelengths, without any compressive strain of the layer. For germanene, the height difference between two Ge atoms from the same sub-lattice can be as high as 4.7 Å for an undulation length of 81 Å. The deformations are related to slight (lower than 1.7°) bond angle modifications, and the energy cost is remarkably low, lying between 0.1 and 0.8 meV per atom. These undulations modify the electronic structure, opening a gap of 15 meV.

Keywords: germanene, undulations, DFT, rippling

(Some figures may appear in colour only in the online journal)

1. Introduction

Since the first experimental descriptions of silicene [1] and germanene [2, 3], these two-dimensional (2D) crystals are widely explored, in particular because of their numerous expected applications [4–10], for example in nanoelectronics, in relation with their high carrier mobility [11–13]. Moreover, they could be used as a spin filter [14], gas separation [15], DNA sequencers [16] or for energy conversion and storage applications [17]. They can also be functionalized with organic molecules to modify their properties [17, 18]. They have been mainly grown on metallic substrates, namely on the Ag(111) surface for silicene [1, 19–21], and Au(111) [2, 22], Ag(111) [23] or Al(111) [3, 24–28] for germanene. However, even if the atoms are arranged in a honeycomb structure, the atomic structure of silicene and germanene is quite different from that expected for a freestanding layer, which is constituted by two equivalent hexagonal sub-lattices, differing by a height difference [29]. In the case of germanene deposited on Ag(111), two different phases are

described, i.e. one which is in part commensurate to the substrate, and a second one close to freestanding germanene [23]. For silicene on Ag(111) and germanene on Au(111) or Al(111), the Si and Ge lattice tends to match that of the substrate, which means that strong interactions between the 2D crystal and the sub-lying surface are present [1, 19, 30–33]. Since the intrinsic electronic properties of germanene and silicene are drastically affected by these interactions [12, 22, 34, 35], different strategies have been proposed to obtain these systems onto other substrates, for which only van der Waals interactions are present. According to density functional theory (DFT) calculations, the 2D layer could be detached, and then deposited on a chosen substrate [36, 37]. On the other hand, germanene has been synthesized by evaporation of Ge, in ultrahigh vacuum, on graphite [38] or MoS₂ [39], and silicene has been obtained on graphite by evaporating Si [40]. The atomic structure of the resulting 2D lattice is close to that of a freestanding layer, and adsorption energy (E_{ads}) calculations indicate a reduction of the interaction strength with respect to metallic substrates. For silicene on graphene, $E_{\text{ads}} = 0.08$ eV per Si atom [41], while on silver the energy lies between 0.46 and 0.49 eV [1, 30, 42, 43]. However, the

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growth of silicene or germanene on these substrates is not easy to carry on [44, 45].

Now, it appears that graphene, the prototypical 2D material, can exhibit out-of-plane deformations, whenever it is suspended or deposited on a substrate [46–50]. In particular, calculations show that graphene naturally wrinkles because of thermal fluctuations [51, 52]. Thus the deposition of germanene and silicene interacting only weakly with the substrate could be made still more difficult if ripples are easily formed. According to molecular dynamics simulations, silicene actually wrinkles, with deformation heights of 3.5 Å at 150 K and 5.4 Å at 300 K [53]. But undulations are not only related to a thermal effect. Indeed calculations indicate that graphene [54], as well as silicene [55], present corrugations at 0 K when applying a compressive strain. However the nature of silicene and germanene is quite different from that of graphene. The latter constitutes the ideal 2D system with sp^2 bonds, while silicene and germanene are buckled and present an sp^2 – sp^3 hybridization, with bond angles of 116° (Si) and 112° (Ge), that is, between 109° (pure sp^3) and 120° (pure sp^2). Since in graphene rippling is related to bond angle modifications [54], the sp^2 – sp^3 hybridization for silicene and germanene, which results in weaker π -bonds [56], may afford an extra degree of freedom with respect to graphene. In other words, silicene and germanene could present undulations without the need of a compressive strain or thermal effect. Indeed, for graphene, rippling (at 0 K) without applied strain means upward displacements of C atoms, thus an increase of the C–C bonds length, while for silicene or germanene a simple angle modification would be sufficient. In this respect it has been shown that the energy cost to move vertically a C atom is much higher than a Si atom [56], and that the Young modulus of graphene ($340 \text{ N} \cdot \text{m}^{-1}$) is larger than that of silicene ($63.8 \text{ N} \cdot \text{m}^{-1}$) [57].

In this paper, by means of DFT, we describe silicene and germanene freestanding layers presenting different wrinkles heights. The calculation cell size is kept constant, i.e. no compressive strain is applied. We show that the rippled layers are stable at 0 K, and that their deformation energy with respect to the flat layer is lower than 1 meV per atom. However, the electronic band structure is clearly affected by the undulation.

2. Calculations methods

The calculations have been performed thanks to the VASP (Vienna *Ab initio* simulation package) code [58–61], in the generalized gradient approximation, using projector-augmented waves [62, 63] and the functional of Perdew, Burke and Ernzerhof [64, 65]. The different parameters have been thoroughly chosen to ensure that the undulations obtained after relaxation were independent of the calculation conditions. In particular, various maximum values for the forces components have been tested, namely $0.01 \text{ eV}\text{\AA}^{-1}$, $0.005 \text{ eV}\text{\AA}^{-1}$ and $0.003 \text{ eV}\text{\AA}^{-1}$. It appeared that convergence is reached at $0.005 \text{ eV}\text{\AA}^{-1}$, which the value used throughout this work. For silicene, a diamond cell of 128 atoms has first been used, with a size of $30.94 \text{ \AA} \times 30.94 \text{ \AA}$. Undulations along

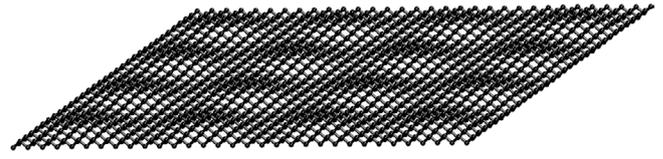


Figure 1. Relaxed silicene layer with undulations in two directions.

the zig-zag atomic chains of the honeycomb lattice have been studied using rectangular meshes constituted of 32, 48, 64 or 80 atoms, with a size of $30.94 \text{ \AA} \times 6.70 \text{ \AA}$, $46.41 \text{ \AA} \times 6.70 \text{ \AA}$, $61.88 \text{ \AA} \times 6.70 \text{ \AA}$, and $77.35 \text{ \AA} \times 6.70 \text{ \AA}$ respectively. For undulations along the armchair atomic chains, the sizes are $7.74 \text{ \AA} \times 26.80 \text{ \AA}$, $7.74 \text{ \AA} \times 40.19 \text{ \AA}$, $7.74 \text{ \AA} \times 53.59 \text{ \AA}$, and $7.74 \text{ \AA} \times 66.99 \text{ \AA}$. For germanene, we restricted our study to the meshes of 64 and 80 atoms, which present the largest deformations. The meshes sizes are $64.97 \text{ \AA} \times 7.03 \text{ \AA}$ or $81.21 \text{ \AA} \times 7.03 \text{ \AA}$ for the undulations along the zig-zag direction, and $8.12 \text{ \AA} \times 56.27 \text{ \AA}$ or $8.12 \text{ \AA} \times 70.33 \text{ \AA}$ for the armchair direction. For all systems the cell height was 20 Å. The Brillouin zone of the diamond mesh has been sampled with $(3 \times 3 \times 1)$ k-points. For the rectangular meshes oriented along the zig-zag direction, $(1 \times 5 \times 3)$, $(2 \times 10 \times 6)$ and $(3 \times 15 \times 9)$ k-points have been tested. We found that convergence is reached for $(2 \times 10 \times 6)$ k-points, which is the sampling we used. For the rectangular meshes oriented along the armchair direction, $(10 \times 2 \times 6)$ k-points have been taken. Band structure calculations have been performed with a cut-off energy of 400 eV for silicene, and 450 eV for germanene. Since the used meshes are larger than the 2D layer primitive cell which contains only two atoms, the bands have been unfolded using the bandUP code [66].

The calculated lattice parameters for germanene (4.061 Å) and silicene (3.868 Å) result from the optimization of the flat layers, using a mesh containing two Ge or Si atoms and $(31 \times 31 \times 11)$ k-points. Note that in this paper we define as ‘flat’ germanene or silicene the usual low-buckled ($\Delta h = 0.688 \text{ \AA}$ for germanene and 0.449 \AA for silicene) honeycomb lattice, for which no ripples are present. The obtained parameter and buckling values are in agreement with previous works [29, 67, 68]. The atomic structures are presented using the visual dynamic software developed by the Theoretical and Computational Biophysics Group in the Beckman Institute for Advanced Science and Technology at the University of Illinois at Urbana Champaign [69, 70].

3. Results and discussion

3.1. Structural study

First we deformed a diamond silicene mesh (128 atoms, mesh size: 30.94 Å) by displacing the Si atoms vertically at different heights. Figure 1 presents several repeated unit cells after relaxation. The system does not appear as a freestanding flat layer, but presents undulations in two directions, namely along armchair and zigzag chains, with a maximum height difference of 0.45 Å between two atoms from the same sublattice. In order to have quantitative results, and to perform

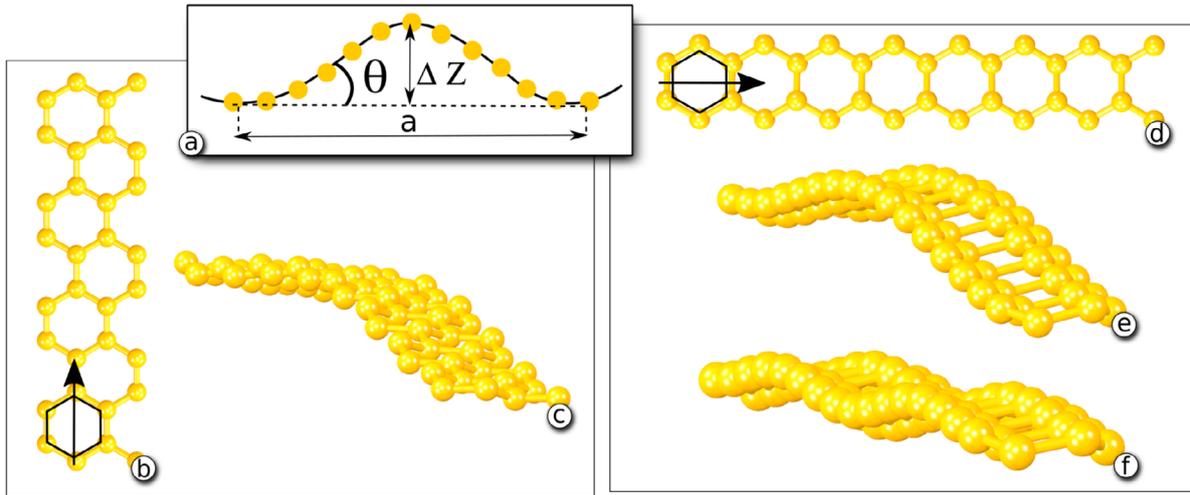


Figure 2. (a) Description of the height difference Δz , the gradient angle θ , and the mesh length a . Ball-and-stick silicene models presenting one single mesh after relaxation with undulations along the armchair direction: (b) top view, mesh of 32 atoms; (c) side-view, mesh of 64 atoms. Undulations along the zig-zag direction: (d) top view, mesh of 32 atoms; (e) side-view, mesh of 64 atoms; (f) side-view, two undulations for a mesh of 64 atoms. The arrows indicate the undulation direction.

calculations on larger systems, we studied 2D layers that are rippled along one single direction, either parallel to the zigzag or to the armchair chains. The rectangular meshes are first deformed by placing all the atoms of a given zigzag or armchair chain at different heights in order to obtain a wave, so that all the atoms (for one of the two sub-lattices) of a chain perpendicular to the undulation direction are at the same height. The mesh size is the same for the flat and the deformed layer. The systems are then relaxed for various initial undulation heights. Figure 2, which displays different meshes after relaxation, shows that the layer is still rippled. We also tested a mesh presenting initially two undulations, which subsist after relaxation (figure 2(f)).

For the different mesh sizes, we find that for a low initial deformation, the system is almost not modified after relaxation. In contrast, when the initial height difference is rather high, the layer tends to minimize the inter-atomic forces, and to reduce the undulation height. In fact, each mesh size can be related to one maximum value for Δz , where Δz is the height difference between the highest and the lowest atom for a given sub-lattice (see figure 2(a)). One can see, in figure 3(a), that Δz_{\max} , i.e. the highest value for Δz , increases with the mesh length, and ranges between 0.67 Å and 4.65 Å. It appears that the unidirectional ripples can be fitted by means of a cosine function. More precisely, the positions of the atoms belonging to the highest sub-lattice are given by $z(x) = z_{\max} \cos(Kx)$. For example, for undulations oriented along the zig-zag direction, the values for the 80 atoms silicene (germanene) mesh are $z_{\max} = 2.04$ Å (2.25 Å) and $K = 0.0812$ Å⁻¹ (0.0774 Å⁻¹).

Now the question is to know whether the augmentation of the maximal height variation is only related to the increasing mesh length. Thus we calculated the gradient angle θ in the following way: $\tan \theta = \frac{\Delta z_{\max}}{0.5a}$, where a is the mesh length. According to figure 3(b), the gradient angle θ lies between 2.8° and 6.7°, and, for a given mesh size, is larger for germanene

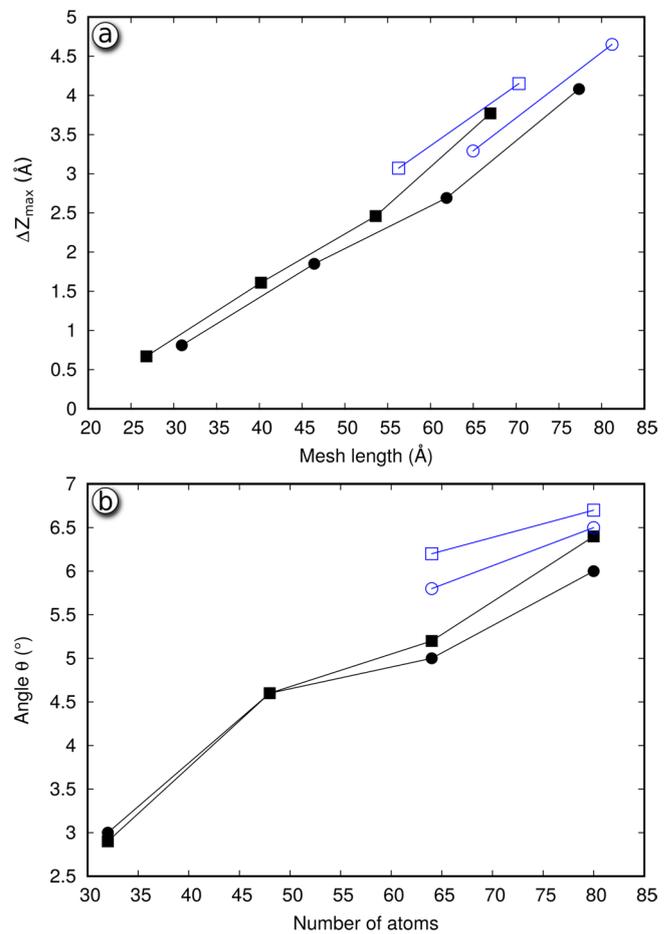


Figure 3. (a) Maximum height difference Δz (in Å) as a function of the mesh length (in Å); (b) gradient angle θ (in °) as a function of the number N of atoms in the mesh. The solid (empty) symbols correspond to silicene (germanene). For germanene, only the largest meshes are presented in order to obtain the trends. The squares (circles) refer to undulations oriented along the armchair (zig-zag) direction.

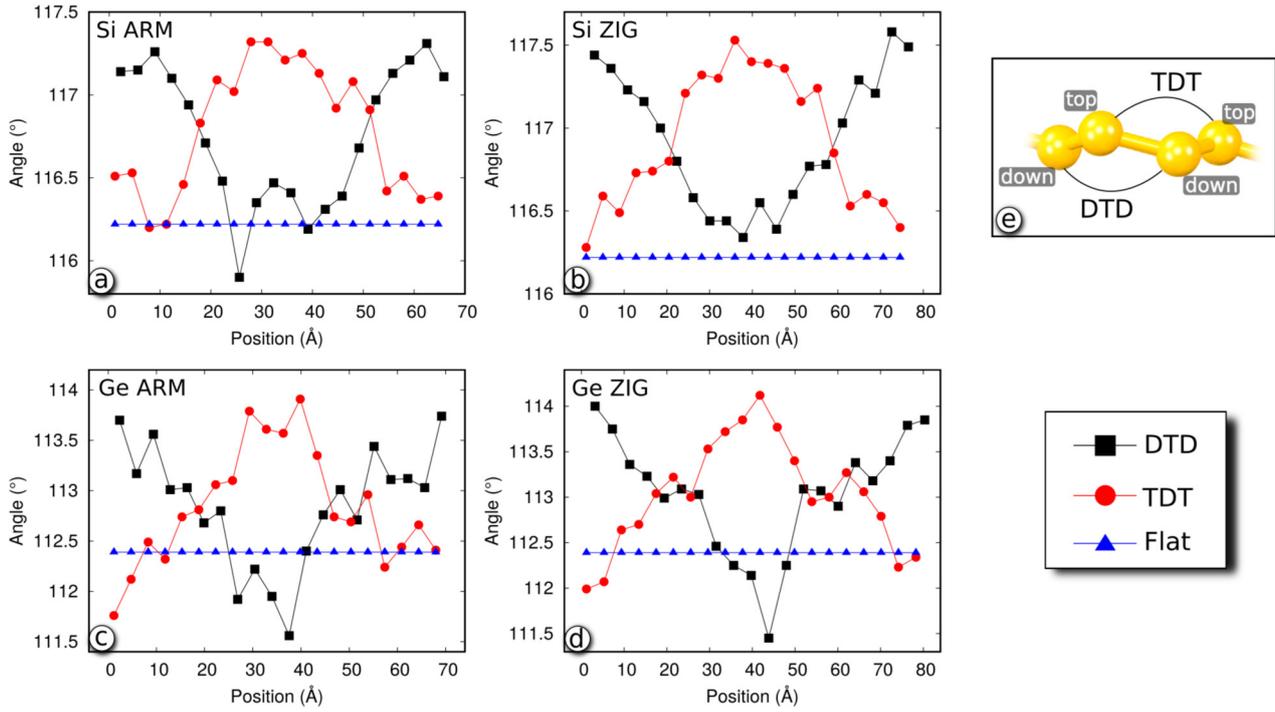


Figure 4. Bond angles (in $^{\circ}$) as a function of the atom position (in \AA) within the atomic chain, for meshes containing 80 atoms. The circles (squares) correspond to TDT (DTD) bonds, and the triangles to the flat freestanding layer. (a) Silicene, armchair direction; (b) silicene, zig-zag direction; (c) germanene, armchair direction; (d) germanene, zig-zag direction; (e) sketch presenting the TDT and DTD angles.

Table 1. Energy per atom and deformation energy, in eV, for silicene and germanene as a function of the atoms number N in the mesh, for one undulation per mesh along the armchair or zigzag direction.

		Silicene				Germanene	
N (atoms number)		32	48	64	80	64	80
Armchair	Atom energy	-4.7848	-4.7848	-4.7848	-4.7842	-4.0126	-4.0124
	Deformation energy	0.0002	0.0002	0.0002	0.0008	0.0007	0.0009
Zigzag	Atom energy	-4.7849	-4.7846	-4.7846	-4.7843	-4.0125	-4.0125
	Deformation energy	0.0001	0.0004	0.0004	0.0007	0.0008	0.0008

than for silicene. Moreover, it increases with the number of atoms N within the mesh. In other words, the maximum height variation is not just proportional to the undulation length, since in that case θ would be similar for the different values of N . Thus we are looking for what induces the augmentation of the gradient angle.

Our calculations show that the layer deformation is not related to a bond extension, since the Si-Si (Ge-Ge) length lies between 2.28 \AA and 2.29 \AA (2.45 \AA and 2.46 \AA), while for the flat layer the value is 2.28 \AA (2.44 \AA). As a result, the ripples must result from a variation of the bond angles with respect to that of the flat layers, namely 116.22 $^{\circ}$ for silicene, and 112.41 $^{\circ}$ for germanene. It appears that the mean bond angle actually increases, but only slightly, from 0.1 $^{\circ}$ to 0.7 $^{\circ}$. Therefore it is useful to have a picture of the local angles variations, as displayed in figure 4, which gives the bond angle value for every Si or Ge atom along an armchair or zigzag chain in one mesh. Two types of bonds have to be distinguished, as indicated in figure 4(e), namely down-top-down (DTD) bonds or top-down-top

bonds (TDT). Note that for a flat layer the DTD and TDT bonds are the same since the sub-lattices of the top and down atoms are equivalent.

The difference between the largest and smallest bond angle is about 1.2 $^{\circ}$ for silicene and 2.3 $^{\circ}$ for germanene. The atom for which the DTD bond angle is maximum is the nearest neighbor of the one exhibiting the lowest TDT bond, and vice versa. Moreover the largest deformations with respect to the flat layer are located at the convex parts of the layer. We should note that, according to the calculations of Peng *et al*, the Young modulus of buckled silicene (63.8 $\text{N} \cdot \text{m}^{-1}$) is lower than that of flat silicene (71.2 $\text{N} \cdot \text{m}^{-1}$) [57], which indicates the additional degree of freedom of sp^2 - sp^3 bonds with respect to pure sp^2 ones. It appears that the Ge bonds are more easily deformed than the Si ones, which is also reflected in a Young modulus of 44 $\text{N} \cdot \text{m}^{-1}$ [71], that is, lower than for buckled silicene. Finally, we calculated the average effective bond angles (AEBA) which allows to indicate the sp^3 (AEBA1) or sp^2 (AEBA2) character of a bond hybridization [72]. The AEBA is obtained as following:

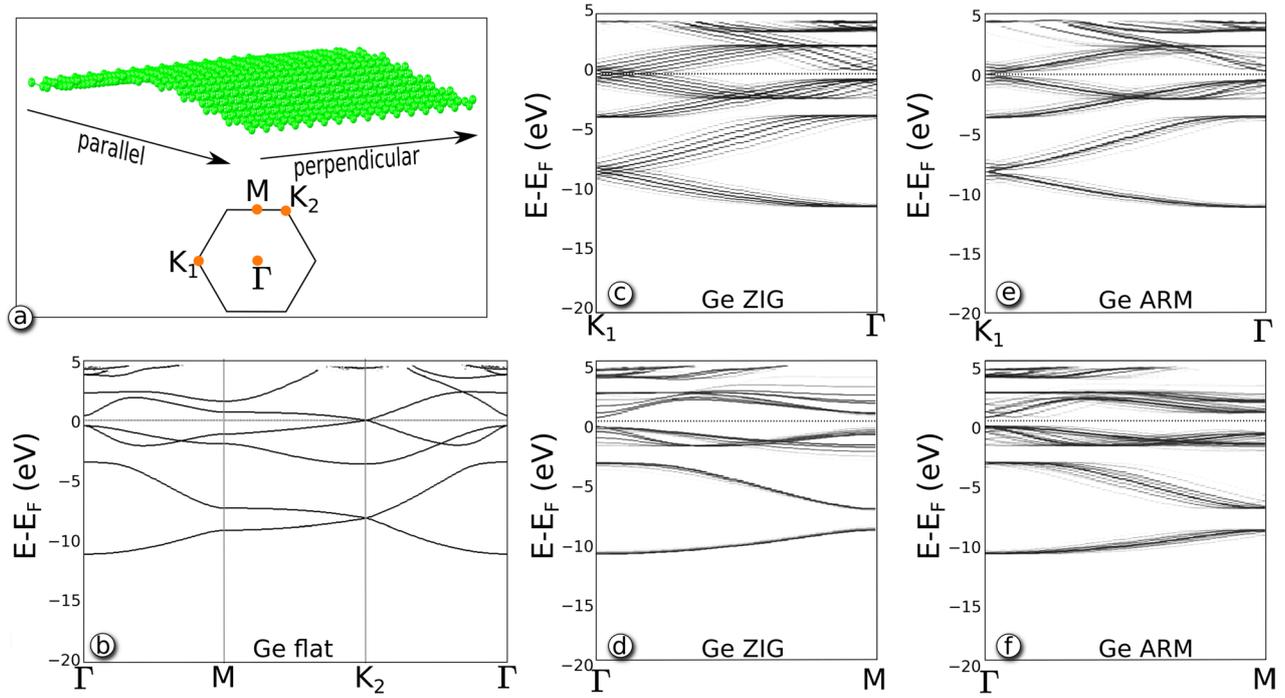


Figure 5. Band structure of germanene for a mesh comprising 80 atoms for (b) a flat layer, (c) undulations oriented along the zig-zag direction, the $K_1\Gamma$ direction (indicated in (a)) is parallel to the undulation; (d) undulations oriented along the zig-zag direction, the ΓM direction is perpendicular to the undulation; (e) undulations oriented along the armchair direction, the $K_1\Gamma$ direction is perpendicular to the undulation (f) undulations oriented along the armchair direction, the ΓM direction is parallel to the undulation. For the flat layer, the K_1 and K_2 points are equivalent.

$$AEBA = 1 - \frac{\sum_{i=1}^{N_{\text{angle}}} |A - \text{Ang}(i)|}{A \cdot N_{\text{angle}}} \quad (1)$$

with $A = 109.47^\circ$ for AEBA1, and $A = 120^\circ$ for AEBA2 [72]. For flat silicene, AEBA1 = 0.938 while AEBA2 = 0.968, indicating that the hybridization is more sp^2 than sp^3 , as mentioned in the work of Guo *et al.* For a silicene mesh containing 80 atoms, AEBA1 = 0.932 and AEBA2 = 0.974 (zig-zag direction), or AEBA1 = 0.933 and AEBA2 = 0.973 (armchair direction). We can see that rippling induces a slight diminution of the sp^3 character, and thus an increase of the sp^2 nature of the bond. With regard to germanene, we obtain AEBA1 = 0.973, 0.967, and 0.969 for the flat layer, the system undulated along the zig-zag direction, and along the armchair direction, respectively. The values for AEBA2 are 0.937, 0.942, and 0.940. Thus, for germanene, the hybridization is more sp^3 than sp^2 for both the flat and wrinkled layers. However, as for silicene, there is an augmentation of the sp^2 nature of the hybridization upon rippling. The influence of this wrinkling on the silicene and germanene total energy is the subject of the following section.

3.2. Energetic study

In table 1, we compare the energy per atom for various mesh sizes to that corresponding to the flat layer, namely -4.7850 eV and -4.0133 eV for silicene and germanene, respectively. The data are taken for the systems presented in figure 3, which exhibit the largest height difference Δz_{max} .

Clearly the energy difference between the wrinkled and the flat layers, which ranges between 0.1 and 0.8 meV per atom, is very low, which is in line with the very small bond angles deformations. Thus the different configurations can be considered as energetically equivalent. Moreover, for height differences lower than Δz_{max} (for a given mesh size a), the deformation energies are smaller than those given in table 1. In other words, an infinity of energy-degenerated configurations can be found, with various undulation lengths a , and with various height deformations Δz , varying continuously from $\Delta z = 0$ to $\Delta z = \Delta z_{\text{max}}$ (a). There is no energy barrier between two different configurations, and one given configuration is not more or less stable than another. We must emphasize that for graphene the energy cost due to ripples formation at 0 K, with a gradient angle smaller than 10° , lies below 1 meV per C atom [73]. However one has to keep in mind that, contrary to silicene and germanene, undulations in graphene result from a compressive strain.

3.3. Electronic study

In freestanding silicene or germanene, the atomic environment is the same for all atoms. This is not the case in a rippled layer, since the bond angles differ from one atom to another, as shown in figure 4. Thus the electronic structure is expected to change upon wrinkling. We performed band structure calculations for the germanene mesh of 80 atoms, which is the system displaying the largest angular modifications. The results are presented in figure 5, for both the flat and

undulated layer. The points in the Brillouin zone have been chosen in the following way: when the germanene is rippled along the zigzag atomic chains, the $K_1\Gamma$ (ΓM) direction is parallel (perpendicular) to the undulation (see figure 5(a) and top-views in figure 2). In contrast, when the germanene is rippled along the armchair atomic chains, the $K_1\Gamma$ (ΓM) direction is perpendicular (parallel) to the undulation.

It appears that, for the undulated layer, the bands characterizing the flat layer are still visible. However they are split because the atomic sites are not equivalent when the system is wrinkled. Moreover our calculations show that there is a gap opening at the K_1 point of about 15 meV for both undulations directions. We would like to emphasize that for corrugated graphene, the maximum gap value is 5 meV for a gradient angle of 10° [73]. Here the gradient angle is lower than 7° (see figure 3), for a gap of about 15 meV. Thus rippling has a larger effect for germanene than for graphene. Moreover, according to figure 4, the Ge–Ge–Ge bond angle varies from -0.7° to 1.5° with respect to flat germanene. Now, Wang *et al* have shown that a gap of 13.7 meV appears, when toluene is physisorbed on freestanding germanene, while the bond angle modifications with respect to pristine germanene lie between -1.4 and 0.7° [74]. Thus the gap opening may be related to bond angle modifications. However, in this latter case the germanene deformation is induced by the presence of physical interactions with the molecule, whereas for undulated germanene, the gap opening results from an internal modification of the system.

Finally, one can see in figure 5 that the band structure depends on the orientation of the undulation. When the bands are analyzed along a direction which is parallel to the undulation (figures 5(c) and (f)) the bands resulting from the splitting exhibit a larger weight and a larger energy extension than in the case of a direction perpendicular to the undulation (figures 5(d) and (e)). Indeed, in figures 5(c) and (f), the atoms of a given atomic chain are positioned in various heights since the undulation is parallel to the chain. In contrast, when the $K_1\Gamma$ or ΓM directions are perpendicular to the undulation, the atomic z positions for a chain are similar, while the height of the different chains varies along the mesh. This anisotropy in the atomic positions results in an anisotropy in the electronic structure.

4. Conclusion

2D materials such as silicene and germanene can be rippled without noticeable total energy difference with respect to the flat layers. The undulations are not related to an augmentation of the bond length, but to slight modifications of the bond angles. The addition of the different bond angles deformations induces an increase of the undulation height with the undulation length. As a result, the atoms present various atomic environments, which induce a splitting in the band structure and a gap opening of about 15 meV. This rippling effect is quite different from what is observed for graphene. Since the latter is characterized by sp^2 C–C bonds, undulations at 0 K are obtained only after a compression of the system. In

contrast, silicene and germanene may wrinkle without applied strain because of the softness of the sp^2 – sp^3 bond angles. This property can probably be extended to other low-buckled 2D systems formed from column IV elements, such as stanene [75, 76], or plumbene [77, 78].

Finally, the usual picture of silicene or germanene as a flat layer is largely incomplete. This is only one conformation among many other ones, for which the systems present undulations at 0 K with various heights and lengths, but with similar total energy. It can be expected that the thermal energy brought by $T > 0$ will facilitate the formation of ripples in the layer, which must be taken into account if silicene or germanene are to be detached from their growing substrate and deposited on another support.

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